
Collaborative Surveillance of Large Geographic Area by Fleet of Drones

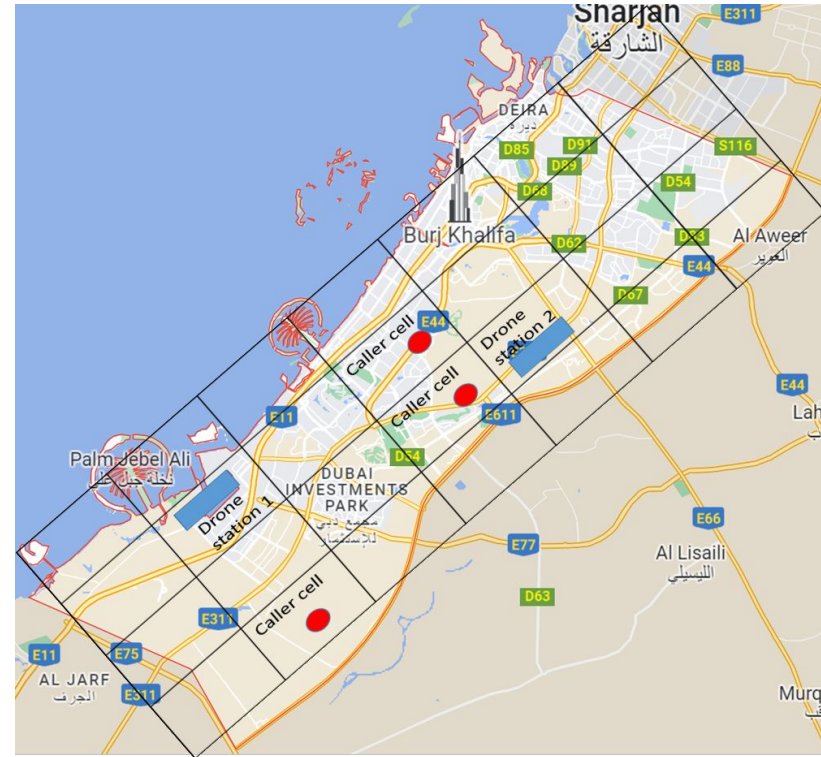
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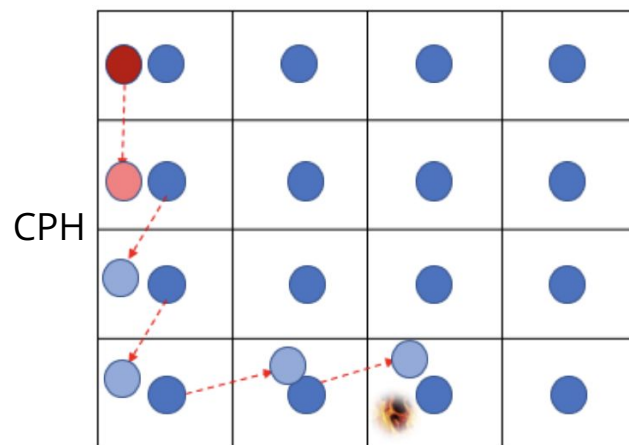
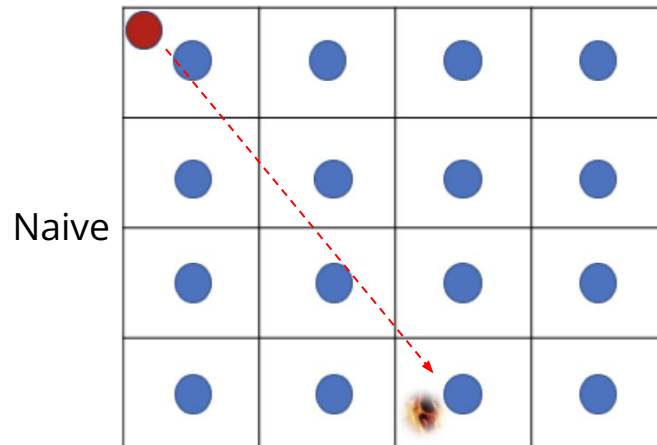
Project Introduction

- Drone Fleet Algorithms
 - Events & Response
- Simulation vs Real-world
- Customizable Setup/Input & Algorithms
- Visualize Runs & Drone Paths
- Request Queue System



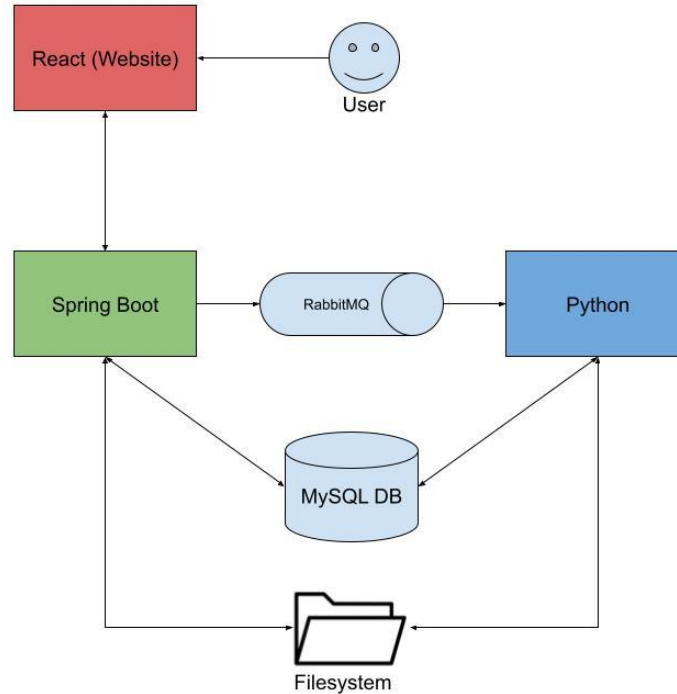
Drone Fleet Algorithms Overview

- Algorithms assume a square grid divided into zones, one drone per zone
- Additional roaming drones fly around to assist scanning
- Goal: When a drone detects an event, roaming drone flies to assist
- 2 Algorithms Provided
 - Naive
 - Coordinated Path-Hop (CPH)

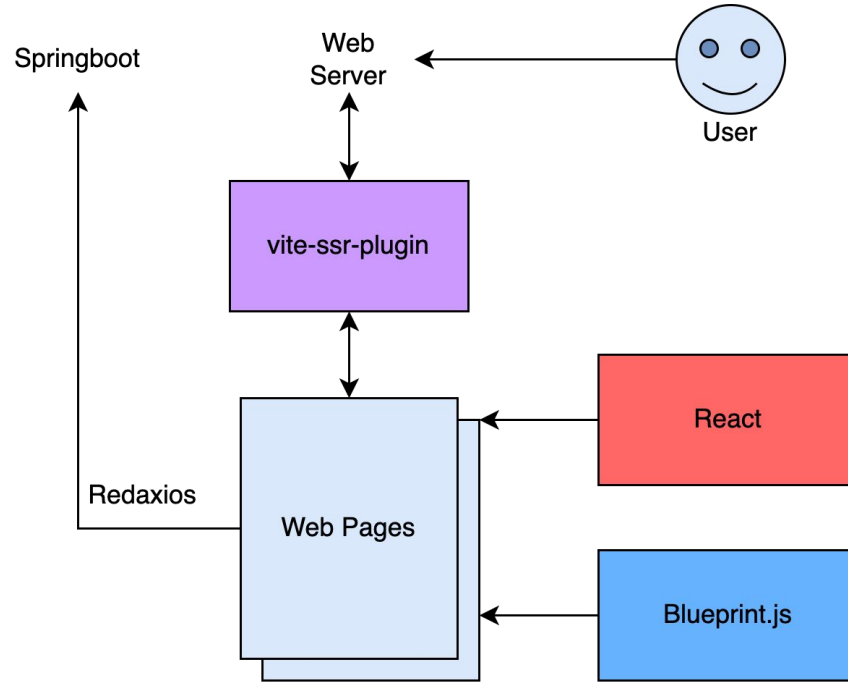


Implementation Architecture

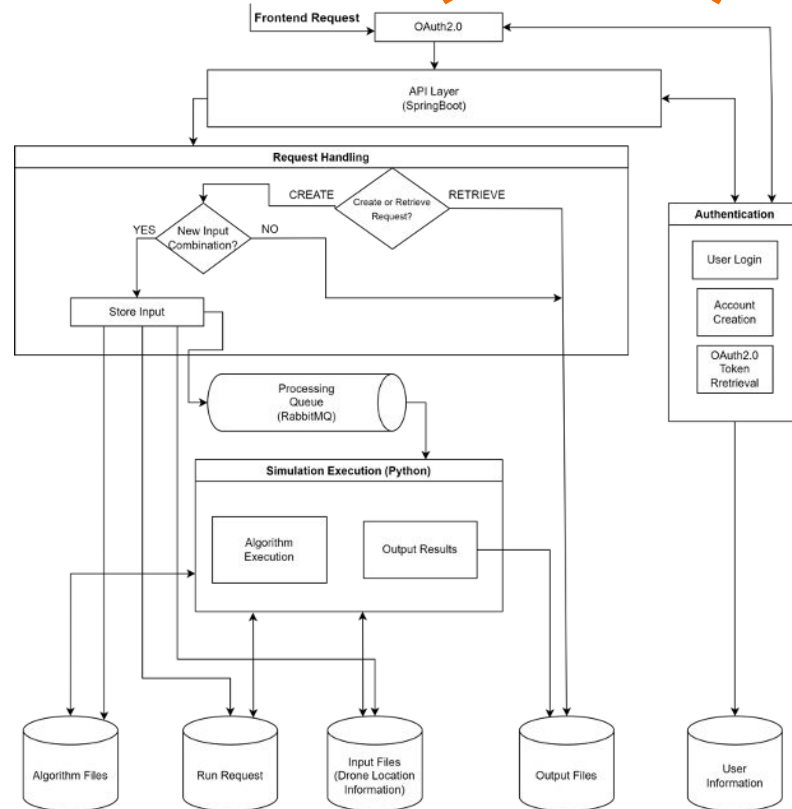
Implementation Architecture (System)



Implementation Architecture (Frontend)



Implementation Architecture (Backend)



Work Accomplishments

Work Accomplishments (Frontend)

Simulation Setup:

- Ability to upload algorithms
- Send run request with specified parameters
- Import data from csv

Simulation Visualization:

- Grid to view drones
- Algorithm comparison

Dashboard:

- Web application navigation
- Display request queue and completion data

The screenshot shows a web interface for simulation setup, divided into several sections:

- Grid Size:** Contains two dropdown menus for 'Rows (required)' and 'Columns (required)', both currently set to '1'.
- Partition:** Contains a dropdown menu for 'Number of Partitions' set to '1'.
- Algorithm:** Contains a dropdown menu for 'Algorithm' set to 'OLD_Naive_alg_file.py', an 'Upload algorithm...' button with a 'Browse' sub-button, and an 'Upload' button.
- Event Data:** Contains a radio button for 'Automatically Generate Data' (unchecked), a dropdown for 'Simulation Duration (required)' set to '1', and a 'Current Time' section with a table.

The 'Current Time' table has the following structure:

	x	y
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		

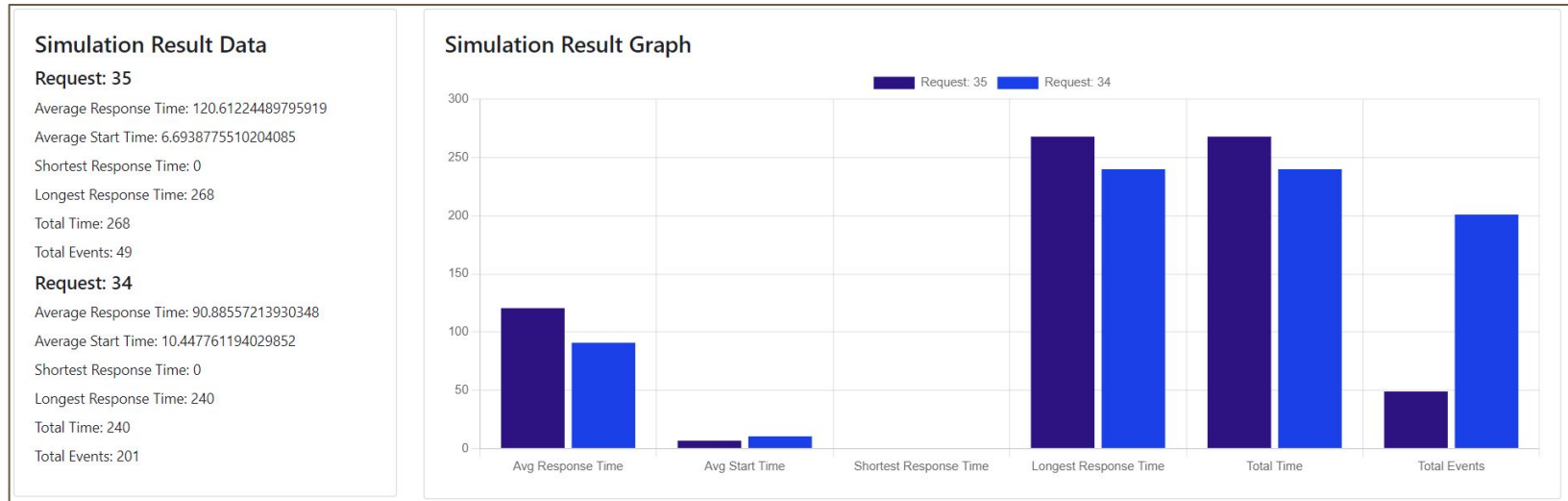
Below the table are buttons for 'Load data from file...' with a 'Browse' sub-button, and a 'Load' button.

At the bottom of the interface is a 'Request Simulation' button.

Work Accomplishments (Frontend)

Simulation Comparison:

- Comparing drone simulation outputs side by side.
- View difference in success criteria for 1 to many Outputs.



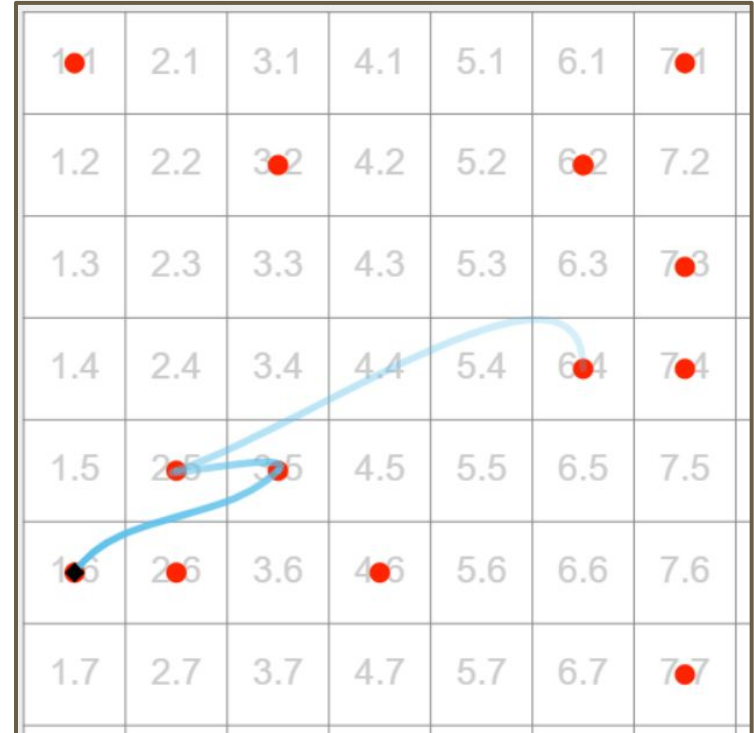
Work Accomplishments (Backend)

Spring Boot:

- User signup & login
- Algorithm file upload
- Run simulation requests
- Enqueue requests
- Simulation status, output & pathing

Python:

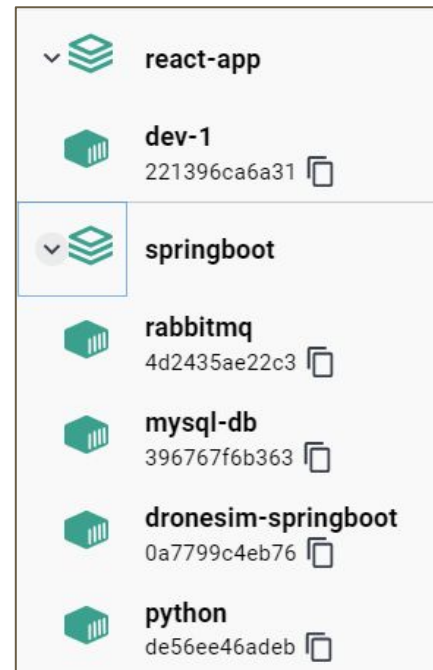
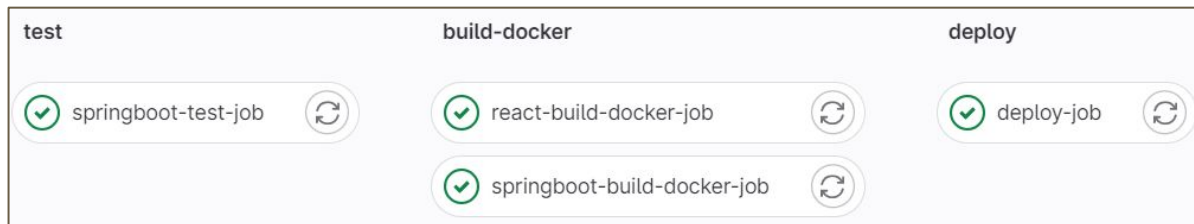
- Receive queued requests
- Drone algorithm execution
- Save output to database
- Create flight paths



Work Accomplishments (Other)

Other:

- Tech stack running in Docker
- CI/CD pipeline automatically deploys changes
- RabbitMQ initialization for queue system
- Token authentication w/Spring Security



Web Application Visuals

Dashboard

Dashboard | File | Logout

Simulation

- Setup a new Simulation
- View Simulation execution
- Compare Simulations


Completed Simulations

Simulation Request #2

Algorithm File ID: 10
Request Time: 4/25/2023, 12:10:19 AM
Execution Start Time: 1/1/1970, 12:00:00 AM
Execution Completion Time: 4/25/2023, 12:10:24 AM

← Previous 1 of 2 → Next

Queued Simulations



No Data
No data is available at this time.

Simulation Setup

Setup | File | Dashboard | Logout

Grid Size

Rows (required)

Columns (required)

Partition

Number of Partitions

Algorithm

CPH

Upload algorithm...

Event Data

Automatically Generate Data

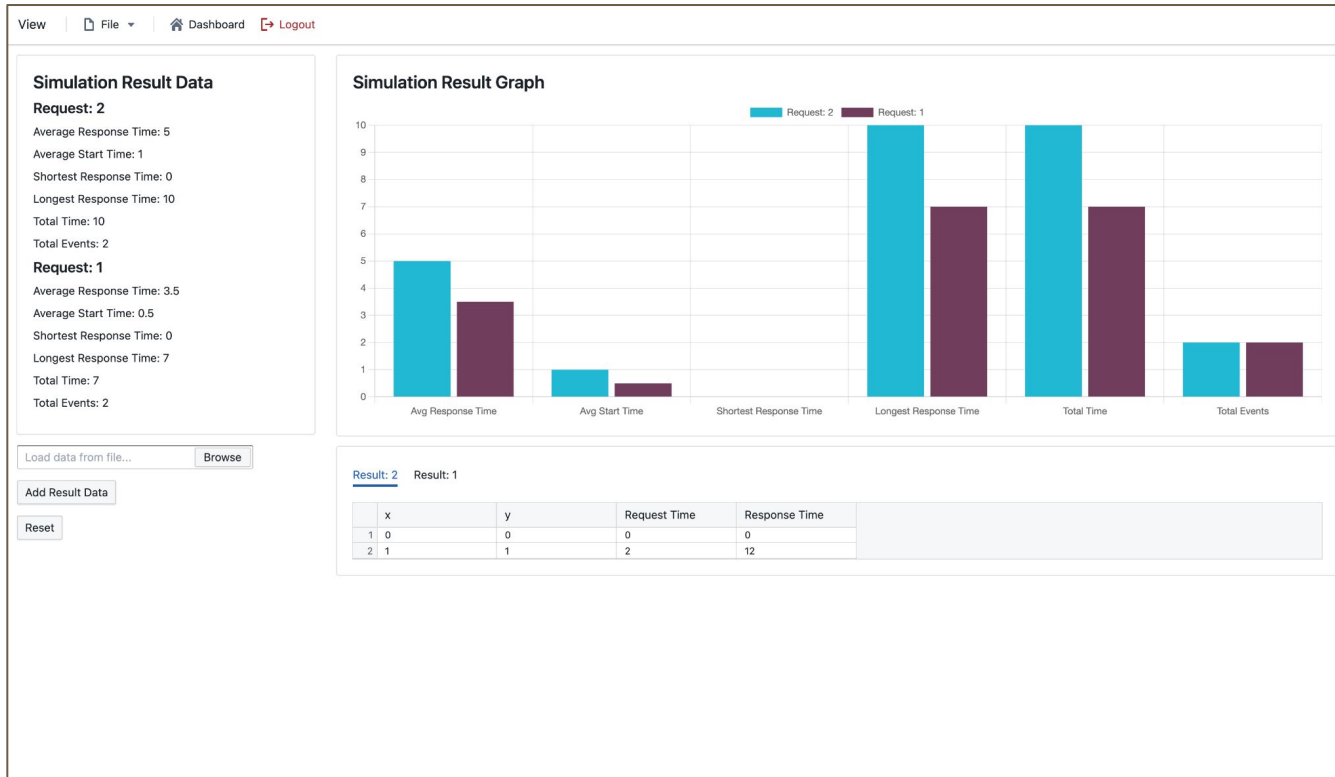
Simulation Duration (required)

Current Time

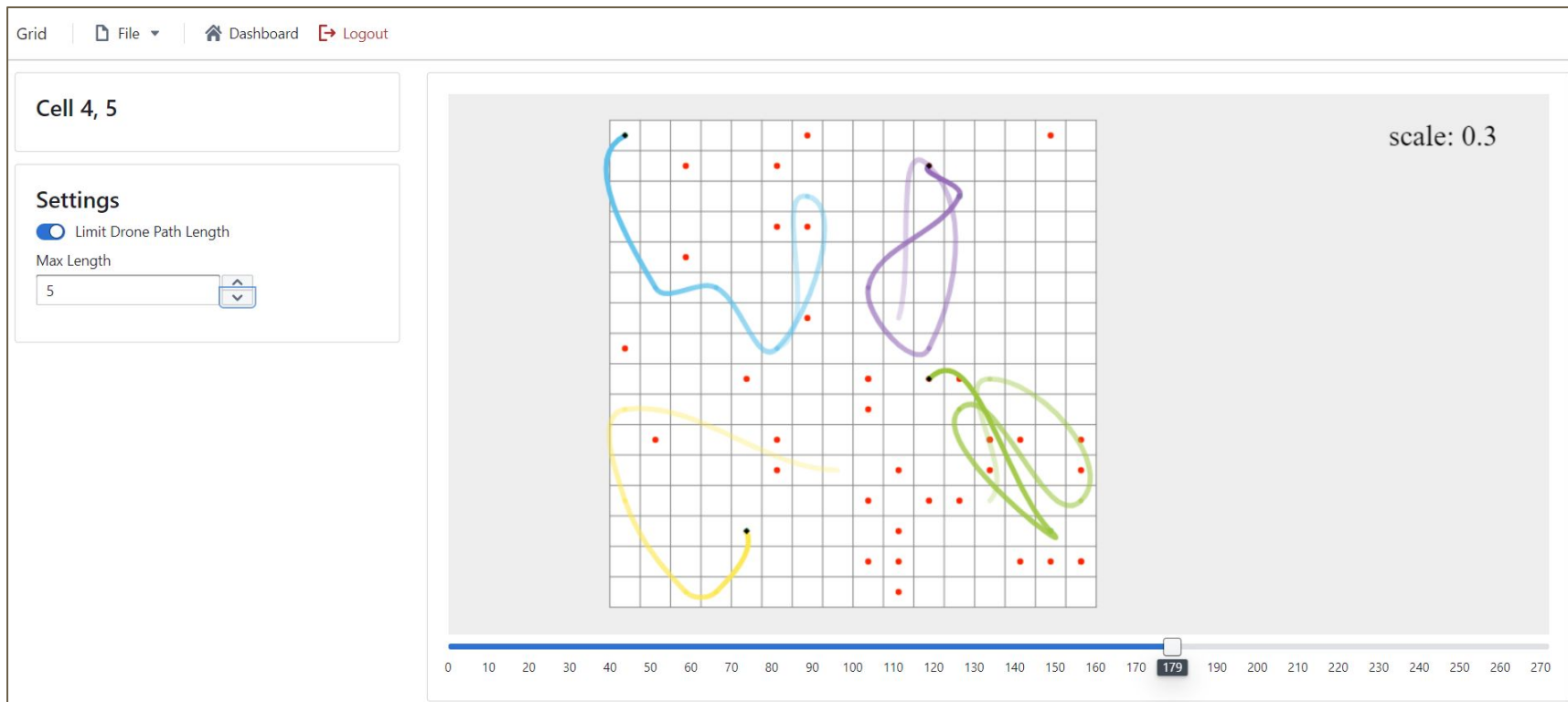
	1	2	3	4
x				
y				
1				
2				
3				
4				
5				
6				
7				
8				
9				
10				

Load data from file...

Simulation Comparison



Simulation Visualization



Team Member Contributions

Key Contributions

Rowan Collins

- *Infrastructure*: Database Initialization
- *Spring Boot*: File uploading, File storage, Code Refactoring
- *Testing*: Spring Boot - Algorithm Files, Input File Service

Joe Edeker

- *Frontend*: Vite (Development, Routing), React + Blueprint, Layouts, Navigation, Setup, View, Grid Visualization

Jaden Forde

- *Python*: RabbitMQ integration, drone algorithm file modification, input loading, algorithm execution, database result logging

Key Contributions

Thomas Glass

- *Frontend*: Setup and Dashboard (React + Blueprint)
- Drone Algorithm Research

Jacob Houts:

- *Infrastructure*: File storage
- *Spring Boot*: Initial Setup, File uploading, Run Initialization, Code Refactoring
- *Frontend*: Simulation Comparison Page, Session Storage, Uploading local I/O
- *Testing*: Spring Boot - Run Requests

Marcus Jakubowsky

- *Spring Boot*: Users, Algorithms, Input, Output, Run Requests, Queue, Path, Authentication
- *Python*: Path mapping
- *Frontend*: Signup, Login, Request authorization
- *Infrastructure*: Docker, RabbitMQ, CI/CD, Server
- *Testing*: Spring Boot - Algorithms, Users, Postman

Challenges & Solutions

Challenges and Solutions

Frontend:

- Page routing
 - Vite-SSR-Plugin
- UI Components
 - Blueprint
- Drone path visuals
 - Custom Polynomial Curve Calculations
- API Request Authentication
 - CORS implementation in Spring

Challenges and Solutions

Backend:

- Running Python algorithms
 - Created Python backend service to handle
- Python algorithm files not standardized (hardcoded)
 - Refactor initial given algorithms & create compliance standard
- Queuing requests
 - RabbitMQ
- Sharing file system across services (docker containers)
 - Use mounted volumes to share file locations
- Tracking repeat simulation setups
 - Hash input combination and store for future reference

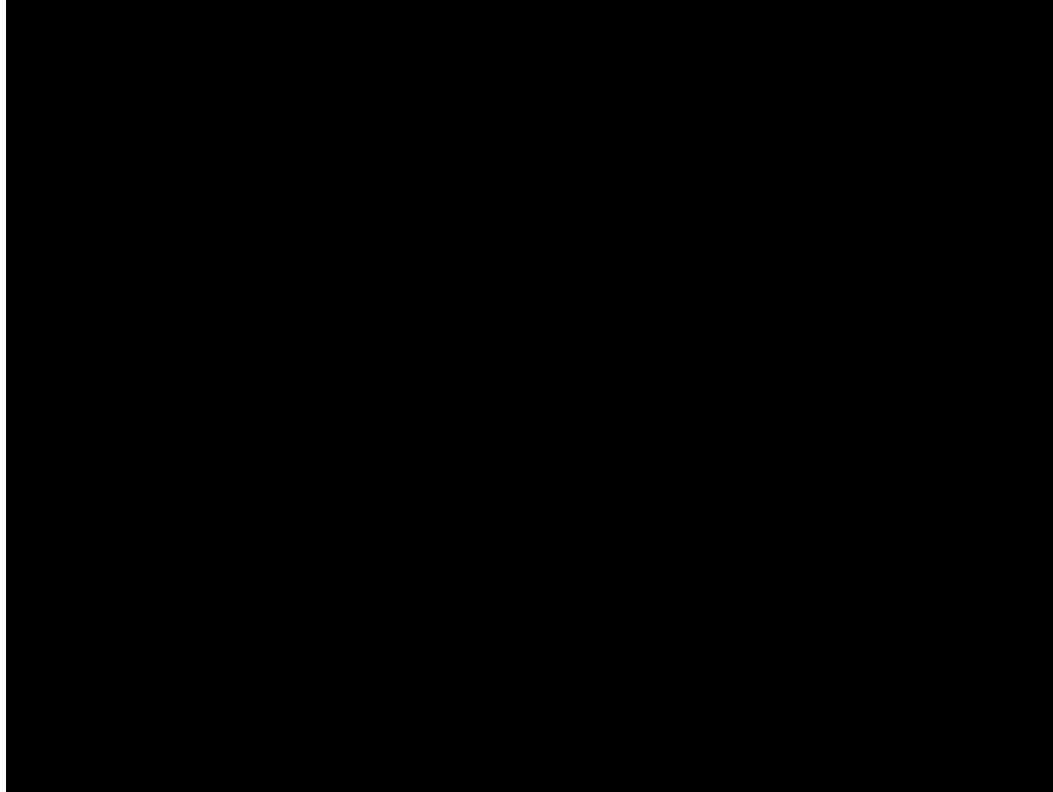
Testing

- Unit Testing
 - JUnit and Mockito
 - Account Creation
 - Run Requests
- Interface Testing
 - Manual Testing
 - SQL Injection Testing
- Python Backend Testing
 - Manual testing with known inputs
- Acceptance Testing
- CI/CD

```
[INFO]
[INFO] Results:
[INFO]
[INFO] Tests run: 20, Failures: 0, Errors: 0, Skipped: 0
[INFO]
[INFO] -----
[INFO] BUILD SUCCESS
[INFO] -----
[INFO] Total time: 5.566 s
[INFO] Finished at: 2023-04-29T20:11:11-05:00
[INFO] -----
```


Demo

Short Demo Video



Future Work

Future Work

- Expand setup parameters
 - Partitions (overlap, sizing)
 - Drone start positions
- Enhance security standards
 - Plaintext login/registration
 - Run simulations in restricted containers
- Additional simulation statistics
- Pathing for CPH algorithm
- Additional/Modular algorithms support
 - Standard format (input/output, runner method)
 - Multiple languages
- Email notifications

Conclusion

Conclusion

Completed Work (Frontend):

- Upload user algorithms & simulation setup
- Output stats comparison
- Path visualization

Completed Work (Backend):

- APIs for user authentication, algorithm upload, run request processing
- Asynchronous queue processing
- Python simulation execution w/response outputs & pathing

Conclusion (Project Objectives)

- Ability to upload input and execute simulations
 - Based on specified parameters
- Algorithms run on backend server
 - Output data to frontend
- Visualize events and drone movements
- Extendable application

What does this mean?

- Display research algorithms in ways which are easy to understand
- Easy to modify for future research algorithms
- Potential for real-world use in drone fleet testing

Thank you!

Questions?